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OUTPUT TESTS OF DRIVER, EXPLOSIVE  
BELLows MK 15 MOD 0

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NOLTR 64-206

OUTPUT TESTS OF DRIVER, EXPLOSIVE  
BELLows Mk 15 Mod 0

Prepared by:  
Sherman L. Min

ABSTRACT: Force-displacement curves for the Mk 15 explosive driver were determined by measurement in a test fixture simulating a particular ordnance application. One hundred units were tested and variability of output was determined. The variability and shape of the force-displacement curves indicate the importance of close control of initial positioning of the driver relative to the parts it operates in such an application.

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U. S. NAVAL ORDNANCE LABORATORY  
White Oak, Maryland

NOLTR 64-206

30 October 1964

OUTPUT TESTS OF DRIVER, EXPLOSIVE BELLows Mk 15 Mod 0

This report presents the results of tests providing characteristic data on the Driver, Explosive Bellows Mk 15 Mod 0 which should be of general use to design engineers. The specific work was required in connection with the employment of this driver in the unlocking device for the POLARIS Mk 2 AFD and was performed under Task No. NOL 417 S/P from the Special Project Office. The opinions and judgments expressed are those of the Air and Surface Mechanical Engineering Department.

J. A. DARE  
Captain, USN  
Commander

*J. H. Armstrong*  
J. H. ARMSTRONG  
By direction

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3	Trace of Bellows Driver Firing Signal
4	Bellows Driver Mk 15 Mod 0 Output Curves (Single Bellows With Simulated Unlock Friction)
5	Schematic Diagram for the Angular Displacement of the Bellows Driver and Paddle in the Bellows Driver Output Test Fixture

## TABLE

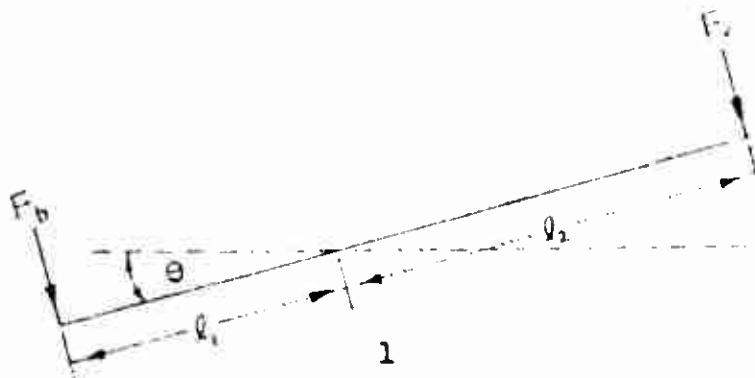
Table		Title
1	Test Data	

INTRODUCTION

1. Failures in the decelerometer unlock of the POLARIS Mk 2 Arming and Fuzing Device (AFD) resulted in the work described herein. Additional gap-test failures (gap between the driver and a paddle-shaped arm of the unlocking device) found at the Naval Ordnance Laboratory, White Oak (NOL(WO) have indicated the need for more information on the driver output. Tests showed that the existence of a ".010" or larger gap caused failures. In order to assure that a single driver has the capability of unlocking the decelerometer, the performance of the driver was investigated and the output test was developed.
2. Hercules Powder Company, contractor for the subject driver, presented a test method where a linear driver output was measured without the frictional force which is encountered in the unlocking device. Although this method should give useful data, it does not solve the gap problem mentioned above.
3. The test fixture shown in Figure 1 gives data for a plot of torque vs angular displacement of the driver in a simulated unlocking device, Figure 4. This plot, with the superimposed decelerometer-unlock operational curve, defines the maximum allowable gap between the driver and the paddle in the unlock. Consequently, the graph indicates the torque required of the driver to assure reliable operation.

THEORETICAL ANALYSIS

4. The output of the driver, as a function of its angular displacement, can be determined by actuating it against a constant load. This load should be sensed by the driver constantly whether it is in motion or at rest. This constant load was obtained by using a "negator" spring which gives a noncumulated force at any length of the spring. The system was proved to be stable by using a high-speed movie camera.
5. Based on the assumption that the force,  $F_b$ , produced by a driver is always normal to the paddle, the system shown in Figure 1 can be represented by a simple free-body diagram as shown below.



Force  $F_v$  is the normal component of the spring force  $F_s$ , and  $\theta$  is the angular displacement caused by the driver. Lengths  $l_1$  and  $l_2$  are the moment arms for the driver and the spring respectively. Length  $l_2$  is four times greater than  $l_1$  to allow a smaller spring force and easier assembly. When the system is in equilibrium, after driver actuation, the torque  $T$  created by the driver is equal to that of the spring. It follows:

$$T = l_1 F_v = l_2 F_s \quad (1)$$

From Appendix A, equation (1) becomes

$$T = l_2 F_s \cos \left\{ 17.5^\circ + \frac{\theta}{2} - \sin^{-1} \left[ \frac{.074}{\sin \left( \frac{\theta + 35^\circ}{2} \right)} \right] \right\} \quad (2)$$

Thus, torque  $T$  can be computed from equation (2) or it can be determined by a torque wrench with respect to  $\theta$ .

6. In order to analyze the effect caused by the gap between the driver and the paddle in the unlock, the angular displacement has been converted to linear displacement along its curved path as shown in Appendix C. Prior to the work described in this report, a maximum gap of .145" could exist in the unlock. The latest revision to the unlock specification allows a maximum gap of .035". A theoretical plot with respect to these two gaps indicates the reliability of the driver.

#### PROCEDURE

7. One-hundred drivers were serialized and their bridge-wire resistances and insulation resistances were recorded. These values were within the specification (WS 1905). The specimens were then subjected to x-ray examination. No defects were found and the specimens were ready for the output test.

8. The test driver was placed in the test fixture in such a way that the front end of the driver was in contact with the paddle. A negator spring with a known spring force was attached to the other end of the paddle. Five different values of spring force were used and twenty drivers were subjected to each spring force. Thus, each spring force determined a point on the output curve.

9. An electrical signal of 4 volts d.c. with one millisecond pulse was used to fire the drivers in accordance with WS 1905F, paragraph 3.4.2.6. The circuit diagram for the test is shown in Figure 2. This diagram shows that the high-speed movie camera (6000 frames per second) closed the circuit. In turn, the pulser generated the required electrical signal to actuate the driver. An oscilloscope was used for visual inspection of the pulse. A typical pulse is shown in Figure 3.

### RESULTS

10. Test data are listed in Table 1 and the output curves are shown in Figure 4. It was observed that the variations in the angular displacements of the drivers had large ranges. The standard deviations  $\sigma$  (see Appendix B) were found to be  $\pm 6.83^\circ$ ,  $\pm 12.2^\circ$ ,  $\pm 8.34^\circ$ ,  $\pm 5.90^\circ$  and  $\pm 4.63^\circ$  for spring forces of 3.70 lbs, 4.49 lbs, 4.80 lbs, 5.47 lbs, and 6.60 lbs. respectively.

11. By measuring 30 drivers, it was found that one third of them were oversized in length. The lengths were approximately .015" longer than the 1.000" maximum specified on BUWEPS drawing 2415726.

### DISCUSSION

12. Figure 4 shows that the critical point for the unlock is at  $25^\circ$  and 7 in-lbs torque. However, the lowest torque found from the test at that particular angle was 9 in-lbs and the average torque at that angle was 11 in-lbs (without gap). For the average values, the factor of safety  $S$  at the critical point is (assuming no gap):

$$S = \frac{\text{output torque}}{\text{working torque}} = \frac{11}{7} = 1.57$$

For the lowest values

$$S = \frac{9}{7} = 1.28$$

Of course, if both drivers are actuated simultaneously and operated independently in the unlock, the safety factor would be doubled.

13. However, the existence of a .035" separation between the driver and the paddle in the unlock would cause the output curve in Figure 4 to shift .035", or about  $5^\circ$ , toward the axis of

ordinates. The shift is justified because the driver will not sense the 7 in-lbs load until it travels the full gap. The gaps are expressed in terms of linear displacement and the relationship between the linear and angular displacements is expressed in Appendix C. It can be seen from the graph that a large amount of energy is wasted because of the spacing. Theoretically, a .145" spacing output curve would pass through the critical point. It is believed that this is a factor that caused the driver to fail to complete its operation during certain operational tests.

14. High speed movies were used to record the angular displacement accurately. After being fired, the driver was annealed by the hot gas and the spring force caused it to retreat immediately as much as  $7^{\circ}$ .

15. The test fixture cavity wall finish was simulated to the "as cast" finish of the unlock. Therefore the wall friction force which restrained the driver movement is included in the output curves. After the driver's output tests the unlock cavity finish was changed to a 25-40 microinch finish, and a dry film lubricant is required to be applied to the cavity and the paddle bearing surfaces. Thus the driver's output in the latter conditions would be increased.

16. Large values in standard deviation,  $\sigma$ , observed from the test could be explained as follows:

a. The wall thickness of the extendable portion of the driver was not uniform. A thinner wall has less restraining force. Also, the physical properties of the bellows probably vary from unit to unit.

b. From a thermodynamic viewpoint, the pressure generated inside the driver is inversely proportional to the volume. Thus, oversized drivers produced less pressure.

c. Even though the explosives used in the drivers were weighed, inherent variations in chemical content are unavoidable.

#### RECOMMENDATIONS

17. Based on the above discussion, the following actions are recommended:

a. Avoid spacing between the driver and the paddle in the unlock by selective assembly.

b. Tighten the contractor's quality control on the driver and all components associated with it in the unlocking device.

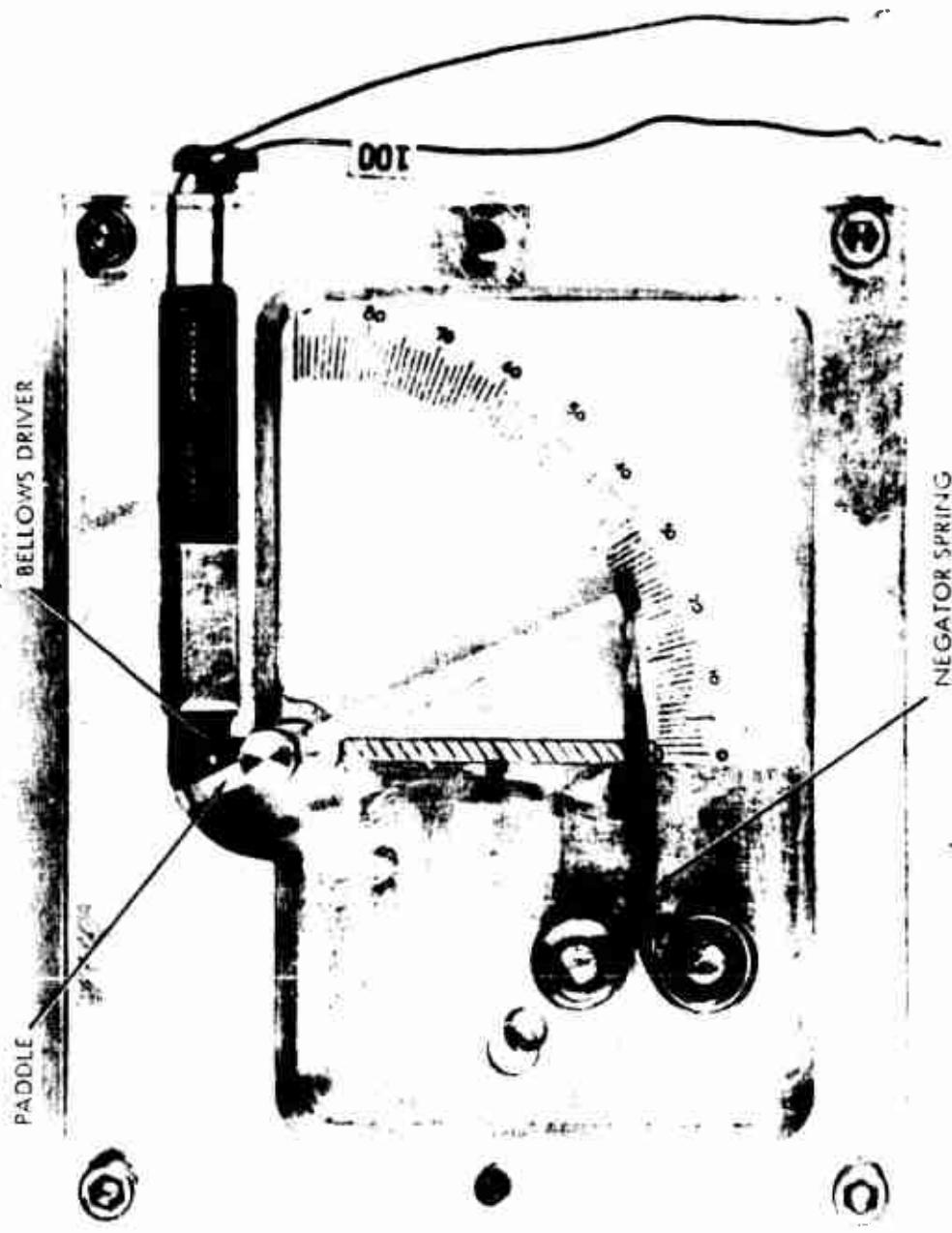


FIG. 1 BELLOWS DRIVER EQUIPMENT FIXTURE

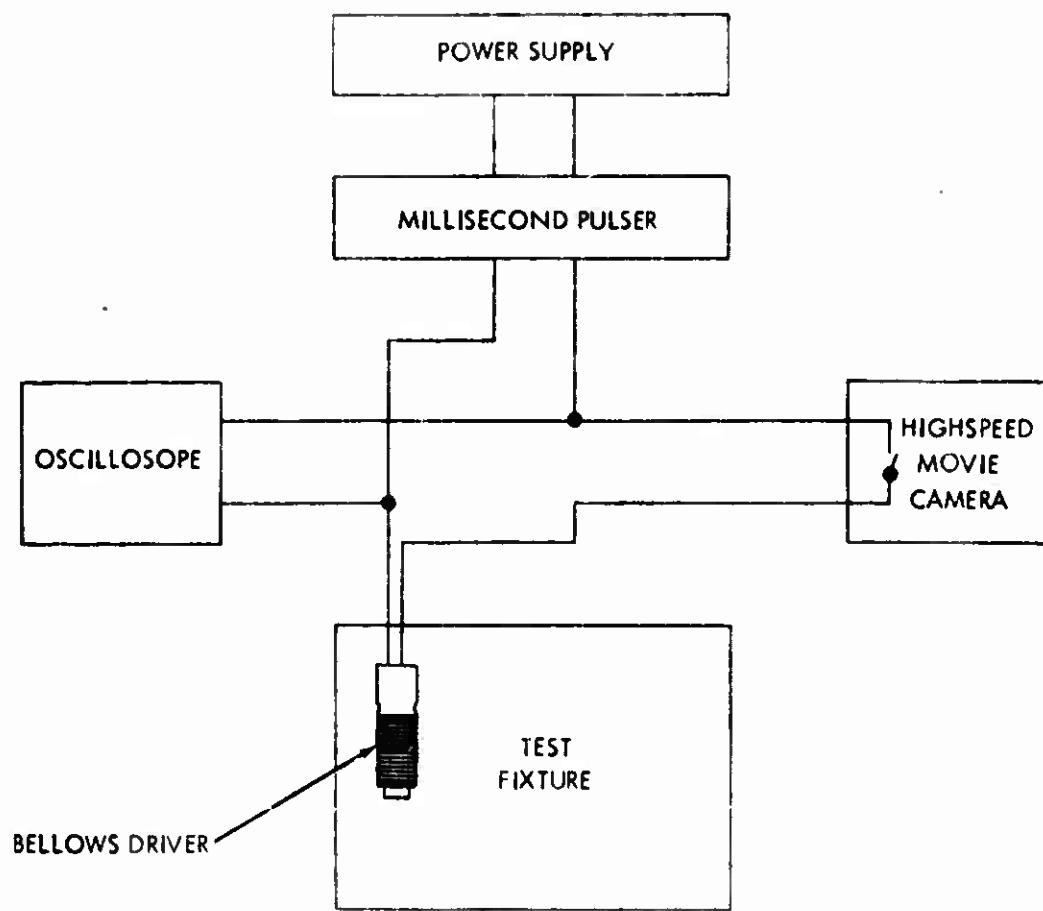


FIG.2 BELLOWS DRIVER OUTPUT TEST CIRCUIT DIAGRAM

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PULSE = 1 VOLT CM

SWEET 0.2 MS CM + FROM RIGHT TO LEFT .

FIG.3 TRACE OF BELLOWS DRIVER FIRING SIGNAL

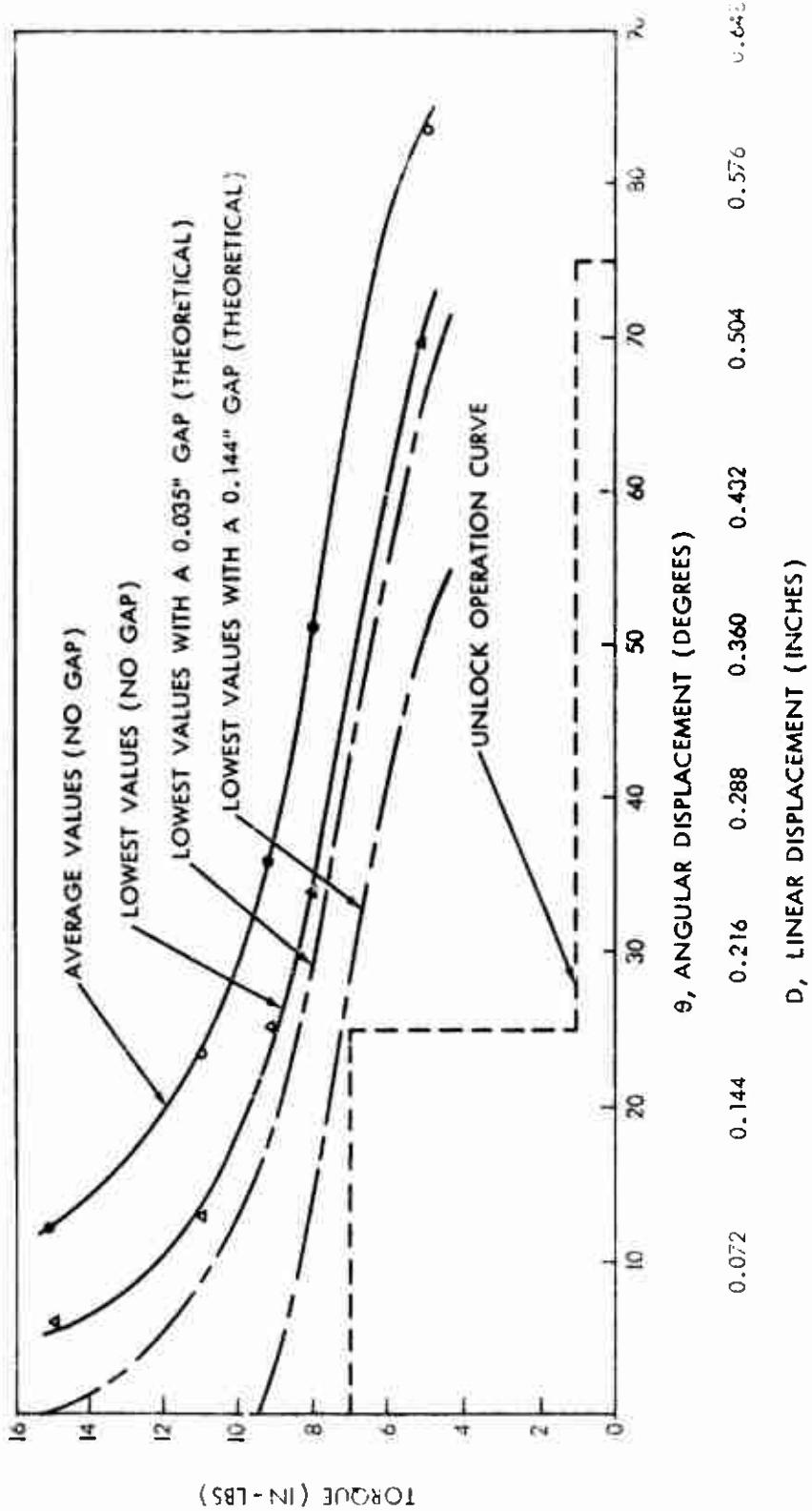


FIG. 4 BELLOW'S DRIVER MK 15 MOD O OUTPUT CURVES (SINGLE BELLOW WITH SIMULATED UNLOCK FRICTION)

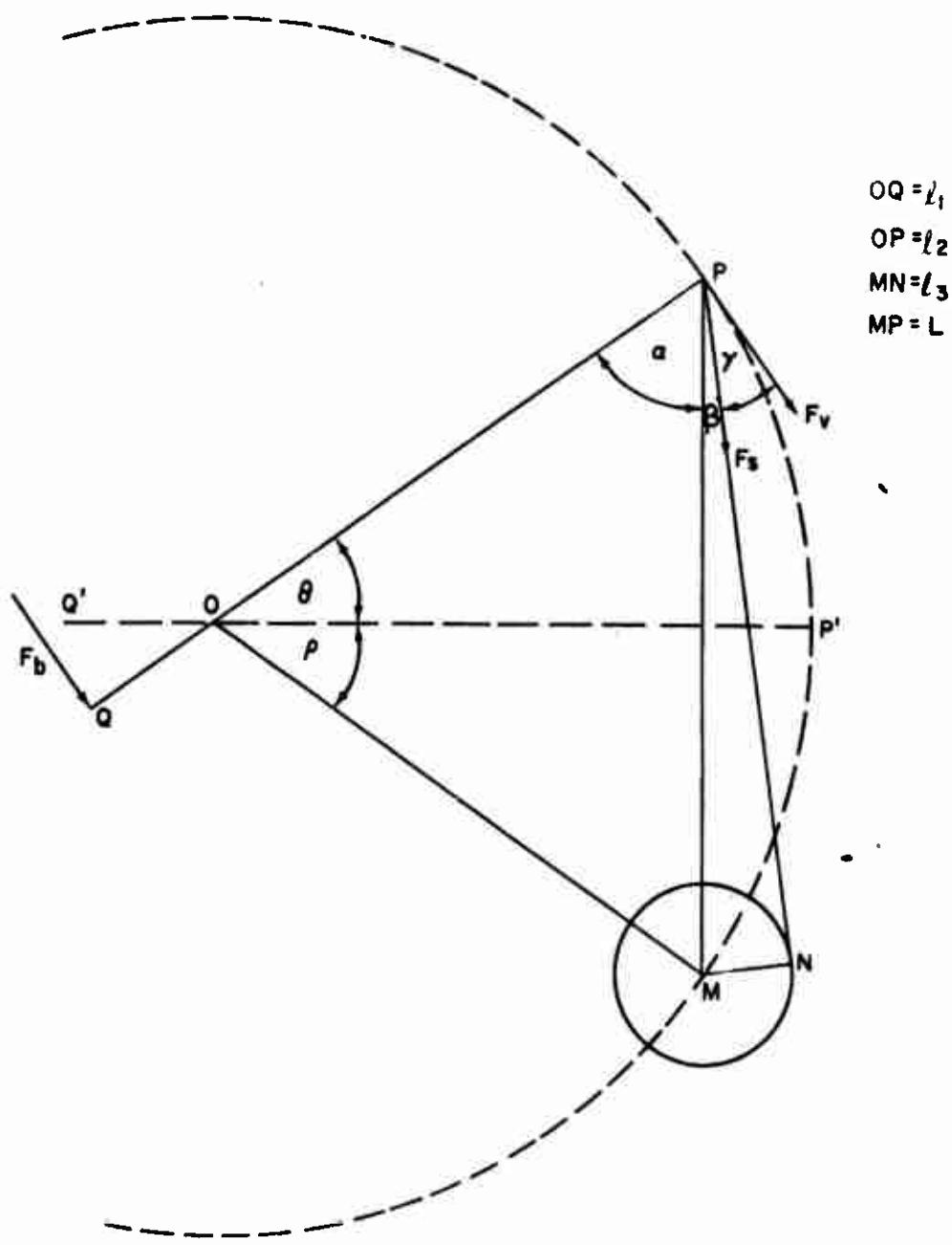


FIG. 5 SCHEMATIC DIAGRAM FOR THE ANGULAR DISPLACEMENT OF THE BELLOWS DRIVER AND PADDLE IN THE BELLOWS DRIVER OUTPUT TEST FIXTURE

TABLE I TEST DATA

SPRING FORCE, ( $F_S$ ) (LBS)	TORQUE ( $T$ )(IN/LBS)	AVERAGE ANGULAR DISPLACEMENT, ( $\bar{\theta}$ ) (DEGREES)	LOWEST ANGULAR DISPLACEMENT, ( $\theta_L$ ) (DEGREES)	STANDARD DEVIATION, ( $\sigma$ ) (DEGREES)
3.70	5.0	83.55	70.0	$\pm 7.01$
4.49	2.0	51.15	34.0	$\pm 12.20$
4.80	9.0	36.95	25.0	$\pm 8.34$
5.47	11.0	23.45	13.0	$\pm 5.90$
6.60	15.0	12.30	6.0	$\pm 4.63$

## APPENDIX A

## Derivation of Equation (2)

1. Referring to Figure 5, the paddle QP is initially located at QP'. When the driver is fired against a negator spring force  $F_s$ , the paddle stops at an angle  $\theta$  depending on the value of  $F_s$ . That is, a small value of  $F_s$  will allow a large angular displacement and a large value of  $F_s$  will permit a smaller angular displacement. Letting

$$l_1 = OQ = \text{driver's moment arm} = .500"$$

$$l_2 = OP = \text{spring's moment arm} = 2.000"$$

$$l_3 = MN = \text{spring's drum radius} = .297"$$

$$L = MP$$

from geometry, it is clear that

$$F_v = F_s \cos \gamma \quad (3)$$

2. In order to determine  $\gamma$ , first let's look at its complementary angle  $\alpha$  plus  $\beta$ . Since

$$L = 2 l_2 \sin \left( \frac{\theta + \rho}{2} \right)$$

$$\sin \beta = \frac{l_3}{L} = \frac{l_3}{2 l_2 \sin \left( \frac{\theta + \rho}{2} \right)}$$

$$\therefore \beta = \sin^{-1} \left[ \frac{l_3}{2 l_2 \sin \left( \frac{\theta + \rho}{2} \right)} \right] \quad (4)$$

But in the isosceles triangle  $\Delta POM$

$$2\alpha + \theta + \rho = 180^\circ$$

$$\therefore \alpha = 90^\circ - \frac{\theta + \rho}{2} \quad (5)$$

$$\text{But } \gamma = 90^\circ - \alpha - \beta \quad (6)$$

Substituting equations (4) and (5) into equation (6), we get

$$\gamma = \frac{\theta + \rho}{2} - \sin^{-1} \left[ \frac{l_3}{2l_2 \sin(\frac{\theta + \rho}{2})} \right] \quad (7)$$

Using  $\rho = 35^\circ$ ,  $l_3 = .297"$ ,  $l_2 = 2.000"$

$$\gamma = 17.5^\circ + \frac{\theta}{2} - \sin^{-1} \left[ \frac{.297}{4 \sin(\frac{\theta + 35^\circ}{2})} \right] \quad (8)$$

Since  $\gamma$  is a function of  $\theta$  only, the torque  $T$  produced by the driver can be expressed in terms of  $\theta$  by the aid of equations (1), (3) and (8). It follows

$$T = l_2 F_s \cos \left\{ 17.5^\circ + \frac{\theta}{2} - \sin^{-1} \left[ \frac{.074}{\sin(\frac{\theta + 35^\circ}{2})} \right] \right\} \quad (9)$$

APPENDIX B

1. The standard deviation  $\sigma$  is defined by the equation

$$\sigma = \sqrt{\frac{\sum (\theta_i - \bar{\theta})^2}{N}}$$

where  $\theta_i$  is the individual angular displacement, and  $\bar{\theta}$  is the average value and  $N$  is the sample size.

## APPENDIX C

1. The linear displacement  $d$  can be expressed in terms of the angular displacement  $\theta$  by the following relationship

$$\frac{d}{\theta} = \frac{\pi R}{180^\circ}$$

where  $R$  is the contact radius from the center of the shaft to the midpoint of the curved slot in the unlock, where the driver is assumed to be in contact with the paddle, and  $d$  is the arc length through which the driver has traveled. Taking  $R = .413"$  from BUWEPS drawing 2420792

$$d = .072\theta \quad (\text{in.})$$

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